

# Théo Morales, Ph.D.

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🌐 Théo Morales

🌐 <http://themorales.com/>



## Employment History

- 2024 – 2026 **Research Fellow.** School of Computer Science & Statistics, Trinity College Dublin, Ireland.
- 2023 **Short-term lecturer.** Fuzhou University & Maynooth University, China.
- 2020 – ... **Programming Tutor.** online and in Dublin, Ireland.
- 2019 – 2020 **Computer Vision engineer (R&D).** Dopli / Cysteme / XLIM, France.
- 2019 **Research assistant.** Artificial Intelligence in Robotics group, Aarhus University, Denmark.
- 2017 – 2019 **Part-time software developer.** Trifork, Aarhus, Denmark.
- 2016 – 2017 **Part-time software developer.** Asimut Software, Aarhus, Denmark.

## Education

- 2020 – 2024 **Ph.D. Computer Science, Trinity College Dublin.**  
Thesis title: *Designing Hand-Object Interaction Representations for Better Grasp Priors.*
- 2017 – 2019 **M.Sc. Computer Engineering, Aarhus University.**  
Thesis title: *Synthetic Images for Convolutional Neural Networks in Autonomous Drone Racing.*
- 2016 – 2017 **B.Eng. Information and Communication Technology, VIA University College.**  
Thesis title: *Pizza Ordering Management System.*
- 2013 – 2016 **DUT. Information and Communication Technology, IUT La Rochelle / VIA University College.**  
Undergraduate IT diploma in Embedded Systems & Signal Processing.

## Research Publications

### Conference Proceedings

- 1 T. Morales, O. Taheri, and G. Lacey, “A versatile and differentiable hand-object interaction representation,” in *2025 IEEE/CVF Winter Conference on Applications of Computer Vision (WACV)*, 2025, pp. 23–33. [🔗 DOI: 10.1109/WACV61041.2025.00013](https://doi.org/10.1109/WACV61041.2025.00013).
- 2 S. Ravi, P. Climent-Perez, T. Morales, C. Huesca-Spairani, K. Hashemifard, and F. Florez-Revuelta, “ODIN: An OmniDirectional INdoor dataset capturing Activities of Daily Living from multiple synchronized modalities,” in *2023 IEEE/CVF Conference on Computer Vision and Pattern Recognition Workshops (CVPRW)*, Los Alamitos, CA, USA: IEEE Computer Society, Jun. 2023, pp. 6488–6497. [🔗 DOI: 10.1109/CVPRW59228.2023.00690](https://doi.org/10.1109/CVPRW59228.2023.00690).
- 3 T. Morales and G. Lacey, “A new benchmark for group distribution shifts in hand grasp regression for object manipulation. can meta-learning raise the bar?” In *NeurIPS 2022 Workshop on Distribution Shifts: Connecting Methods and Applications*, 2022. [🔗 URL: https://openreview.net/forum?id=IKbA3QS7c8X](https://openreview.net/forum?id=IKbA3QS7c8X).
- 4 T. Morales, A. Sarabakha, and E. Kayacan, “Image generation for efficient neural network training in autonomous drone racing,” in *2020 International Joint Conference on Neural Networks (IJCNN)*, 2020, pp. 1–8. [🔗 DOI: 10.1109/IJCNN48605.2020.9206943](https://doi.org/10.1109/IJCNN48605.2020.9206943).

## Skills

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Competencies	📖	Computer Vision (stereo vision, SfM, etc.), Computer Graphics (path tracing, OpenGL, etc.), 4D reconstruction, 3D Gaussian Splatting, NeRF, Mitsuba3, Diffusion Models, Transformers, ...
Languages	📖	Native in French, Fluent in English, near working proficiency in Spanish.
Programming	📖	C, C++, Python, Java, Zig, CUDA, Bash, ...
Web Dev	📖	HTML, CSS, JavaScript, Apache Web Server, PHP.
Misc.	📖	Academic research, teaching, training, consultation, $\LaTeX$ typesetting and publishing.

## Miscellaneous Experience

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### Achievements

2025 📖 **Awarded funding**, Research funding for a project with Dolby.

### Conference Reviewing

2024 - ... 📖 **Reviewer**. CVPR, NeurIPS.

## References

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Available on request.